

Developing the First Milence Electric HGV Charging Hub in the UK

Milence appointed VEV to manage the development of its first UK electric HGV charging hub at Immingham, Able Humber Port, serving UK and Europe.

VEV played a key role in securing the 16,000m² site ideally located for travel connections within the UK and to Europe and with potential for 32 charge points to charge hundreds of vehicles per day. Phase one opens with 8 charging bays.

VEV provided a full turnkey solution from design to construction, creating an advanced HGV charging facility.

From securing power and planning approvals to designing for future solar power and mitigating flood risk, VEV delivered the build in record time, maintaining a sustainable and eco-conscious approach throughout construction.



“Expanding into the UK with our first charging hub in Immingham is a significant milestone for Milence. VEV played a central role in every aspect of the project, from sourcing the prime site to planning, design and construction, managing the delivery of our high-spec HGV hub.”

Anja van Niersen, CEO, Milence



Full design including architecture, electrical and civil design. Future-proofed for expansion to 32 bays.



High-spec site with phase one 8x charging bays served by 400kW DC chargers and power connection of 3.6 MVA power.



Reduced CO₂ impact with fibre concrete. Reduced steel. Roofs built in timber & ready for future solar installation. Bio-diversity increased with trees & grasses.



Established in July 2022 Milence is a joint venture between Daimler Truck, the TRATON GROUP, and the Volvo Group.



The JV is committed to build and operate Europe’s largest public charging network for e-HDV with at least 1,700 high-performance public charging points deployed by 2027.



The goal is to accelerate the transition to zero-emission heavy-duty vehicles, setting the stage for a cleaner, more sustainable tomorrow.



Based in The Netherlands, Milence employs a team made up of over 34 nationalities and views diversity as a strength.